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Paper Code : PE- EE 801B/PE- EEE-801C Power system dynamics & control

UPID : 008279

Time Allotted : 3 Hours

Full Marks : 70

The Figures in the margin indicate full marks.

Candidate are required to give their answers in their own words as far as practicable

## Group-A (Very Short Answer Type Question)

1. Answer any ten of the following : [ 1 x 10 = 10 ]

- (I) Why the analysis of synchronous machine equations in terms of  $dq0$  variables is considerably simpler than in terms of phase quantities?
- (II) The transmission line parameter that represents the decrease in signal strength is \_\_\_\_\_ constant.
- (III) What is instability in a power system?
- (IV) Shunt reactors are connected to long EHV lines to prevent over voltage. (True / False)
- (V) Transient (or large) disturbances are caused by \_\_\_\_\_. (give at least two examples)
- (VI) If  $e$  is the number of elements and  $n$  is the number of nodes in graph, then the element-node incidence matrix will have the dimensions \_\_\_\_\_
- (VII) A matrix will be sparse when its sparsity is greater than \_\_\_\_\_
- (VIII) Under no load or open circuit condition what is the value of  $i_d$  and  $i_q$ ?
- (IX) How the voltage dependency of load characteristics is represented by the exponential model?
- (X) State whether the transient stability limit of a power system increases with the fault clearing time or not.
- (XI) The Power Systems are operated with power angle around \_\_\_\_\_
- (XII)  $Z_{BUS}$  matrix is sparse matrix or full matrix?

## Group-B (Short Answer Type Question)

Answer any three of the following : [ 5 x 3 = 15 ]

2. What is the role of independent pole operation of circuit breaker in transient stability enhancement? [5]
3. Write the assumptions made in modeling the synchronous machine in stability analysis of power system network. [5]
4. With the help of a neat block diagram, explain different operating states of a typical power system network. [5]
5. Distinguish between Eigen values and Eigenvectors. [5]
6. Discuss the advantages of delta -P - omega stabilizer over delta – omega stabilizer. [5]

## Group-C (Long Answer Type Question)

Answer any three of the following : [ 15 x 3 = 45 ]

7. A 555 MV A, 24 kV, 0.9 p.f., 60 Hz, 3 phase, 2 pole synchronous generator has the following inductances and resistances associated with the stator and field windings: [ 15 ]

$$\begin{aligned}
 l_{aa} &= 3.2758 + 0.0458 \cos(2\theta) \text{ mH} \\
 l_{ab} &= -1.6379 - 0.0458 \cos(2\theta + \pi/3) \text{ mH} \\
 l_{afd} &= 40.0 \cos \theta \text{ mH} \\
 L_{ffd} &= 576.92 \text{ mH} \\
 R_a &= 0.0031 \Omega \\
 R_{fd} &= 0.0715 \Omega
 \end{aligned}$$

- a) Determine  $L_d$  and  $L_q$  in henrys.
- b) If the stator leakage inductance  $L_l$  is 0.4129 mH, determine  $L_{ad}$  and  $L_{aq}$  in henrys.
- c) Using the machine rated values as the base values for the stator quantities, determine the per unit values of the following in the  $L_{ad}$  base reciprocal per unit system:

$$L_l, L_{ad}, L_{aq}, L_d, L_q, L_{afd}, L_{ffd}, L_{fd}, R_a, R_{fd}$$

8. (a) From fundamentals derive the swing equation of a single generator connected to an infinite bus [ 8 ]

- (b) A 500MW, 21kV, 50Hz, 3-phase, 2-pole generator having a rated pf of 0.9 (lagging), has a moment of inertia of 27500 kg-m<sup>2</sup>. Find inertia constant H in MJ/MVA. [ 7 ]
9. (a) Explain the following terms: Local modes, inter-area modes, control modes, torsional modes. [ 10 ]
- (b) Find the frequency of oscillation for a synchronizing coefficient of 0.6, inertial constant H = 4 and frequency of 50Hz. [ 5 ]
10. Explain the performance of synchronous machines under steady state conditions by applying the per unit equations [ 15 ]
11. (a) List the fundamental requirements that a properly designed and operated power system should meet. [ 5 ]
- (b) Draw and explain the block diagram of a power system and associated control. [ 10 ]

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